

```
2 "name": "Robot 7M",
3 "version": "0.2",
4 "description": "My
5 "geometry": {
6   "parts": ["board",
7     "length": [800, 200],
8     "movements": {"x": 100,
9       "limits": {"x": [-100, 100],
10         "points": {
11           "ShoulderAxis": "p1",
12           "Elbow": "p2",
13           "Wrist": "p3",
14           "FingerCenter": "p4"
15         }
16       }
17     },
18   "markers": {
19     "210": {
20       "aruco": 210,
21       "attached_to": "board",
22       "description": "Aruco on the
23         positionXYZ": [0, 0, 0]
24     },
25     "204": {
26       "aruco": 204,
27       "attached_to": "base",
28       "description": "Aruco on the
29         movesWith": "x",
30         positionXYZ": ["p2.x - 12", -
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